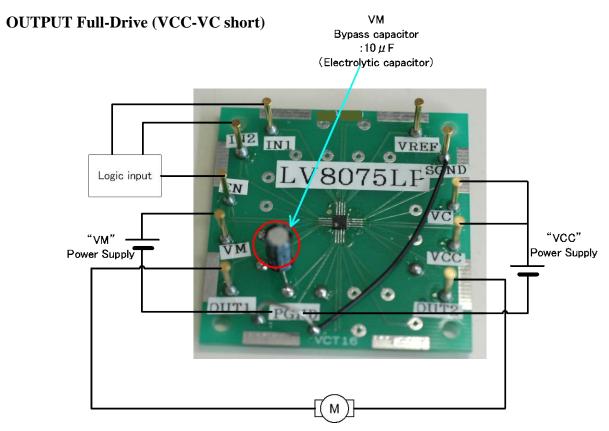
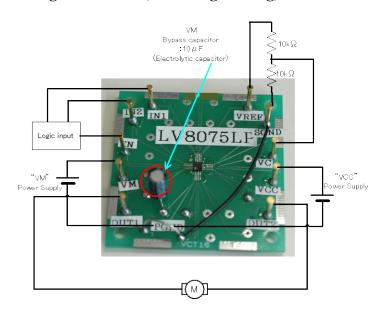


Test Procedure for the LV8075LPGEVB Evaluation Board



LV8075LP (50.0 mm × 50.0 mm × 1.6 mm, glass epoxy 1-layer board) base on VCT16 basic board.

OUTPUT constant voltage 1.5V drive (VC voltage setting)





Supply Voltage:

- VCC (2.5 to 5.5V): Control voltage Supply for LSI
- VM (2.5 to 5.5V): Power Supply for LSI
- VC(0 to VCC):Constant voltage control setting

Testing Procedure for DC Motor Control:

- 1. **Motor Connection:** Connect the Motor(s) between OUT1 and OUT2.
- 2. **Power Supply:** Supply DC voltage to VCC, VM.
- 3. <u>Motor Operation</u>: Set EN and IN1 and IN2 terminals according to the purpose (See LV8075LP datasheet).

Truth TableConstant voltage output H-bridge

| EN | IN1 | IN2 | OUT1 | OUT2 | Mode |
|----|-----|-----|------|------|-------------------|
| Н | Н | Н | L | L | Brake |
| | Н | L | Н | L | Forward evolution |
| | L | Н | L | Н | Reverse rotation |
| | L | L | off | off | Stand by |
| L | - | = | off | off | Stand by |

[&]quot;-" entries indicate don't care state, "off" indicates output off state, insert $20k\Omega$ impedance across PGND.

Constant voltage output value : V (OUT) = V (VC)×2.0

DCmotor load VCC=VM=3V VC=3.0V IN2="H"

(Current waveform example "brake current")

